User requirements for ICRF applications of a co-location satellite

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## User requirements for ICRF applications of a co-location satellite

- 1. ICRF at various frequencies
- 2. General assumptions and requirements for VLBI transmitter
- 3. ICRF applications and special requirements
  - a) Local tie in space
  - b) Determination of AGN core shift
  - c) Determination of AGN core shift VGOS
  - d) Positive effects for EOP
- 4. Recapitulation





## 1. ICRF at various frequencies

- ICRS is the celestial reference system realized by observations of distant active galactic nuclei (AGN)
- Current realizations: ICRF3 (S/X, K, X/Ka) and Gaia-CRF3 (optical)
- **Future:** ICRFs will include VGOS (2.5-14 GHz) and maybe higher frequencies
- Currently each ICRF is derived **independently** → **aligned** afterwards
- Higher frequency ICRFs  $\rightarrow$  higher accuracy with less observations
- Combination of AGN positions among the various wavebands is challenging due to frequency-dependent structure and core shift



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→ Geodesy and astrometry must go hand in hand

GFZ ICRF3: Charlot et al. (2020): A&A Vol. 644, A159, 10.1051/0004-6361/202038368 Gaia: IAU Resolution B3 (2021): https://www.iau.org/static/archives /announcements/pdf/ann21040c.pdf

## 1. ICRF at various frequencies



• Frequency-dependent structure



Fig.: Source model of 0016+731 for the 4 VGOS bands (Xu et al., 2021b, submitted to A&A).



\* Both core shift and structure can also be variable in time.



#### 2. General assumptions and requirements

- VLBI Transmitter: weak broadband noise (similar to AGN)
   → no change at VLBI sites needed
- Satellite speed: slow enough for phase-referencing (nodding-style) GENESIS
- Transmitting antenna requirements:
  - One antenna is probably best option for ICRF applications
  - Operating multiple antennas will cause position offsets of several milliarcseconds (mas) of the respective antenna position in ICRF  $\rightarrow$  Extended VLBI modeling requirements?

AGN ()

ΗΕΙ ΜΗΟΙ ΤΖ

- Calibration of PCO at various frequencies on ground is essential in case of multiple antennas or varying antenna behavior → frequency-dependent `core shift' must be determined
- Satellite antenna pattern must be calibrated in case it is resolved; otherwise point source
- Satellite orientation in space has to be known precisely

Depending on the frequencies, various applications are possible, as follows...



#### 3.a Local tie in space

- VLBI networks used for ICRF determination observe independently at different frequencies (S/X | K | X/Ka | VGOS)
- Satellite emitting the various frequencies = calibrator source to align a multi-wavelength ICRF (based on group delays)
- Contrast to AGN: satellite antenna is **ideal point source** and **frequencydependent position is known** (after calibration)
- → Combination of VLBI networks by constraining the satellite position to be equal for all frequencies applying the local tie in space
- → Combination of independent ICRF realizations
- → User requirement: S/X/K/Ka/VGOS antenna capability



Fig.: Global deformation parameters for orientation offset between the ICRF3 K & X/Ka towards ICRF3 S/X.

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#### 3.b Determination of AGN core shift

- Satellite = calibrator source for precise relative observations (phase-referencing, phase delays) to AGN at various frequencies
  - → AGN core at the various frequencies can be determined relative to each other (for all types of AGN!)
  - → Unsolved problem in astrometric VLBI, unique opportunity
- Absolute position of satellite known → AGN core positions can be transferred to the absolute frame
- $\rightarrow$  Astrophysical studies of AGN
- $\rightarrow$  Approve defining sources for CRF alignment
- → Determination of AGN phase- vs. group delay position offsets, e.g. for observations of radio-faint objects (e.g. radio stars) or for spacecraft tracking





#### Example: Alignment of Gaia DR to ICRF3

- Observations of radio stars are used for verifying the alignment of the bright (G < 13 mag) Gaia frame to ICRF3 S/X: orientation offset and residual spin</li>
- Optically bright stars are usually too faint to be observed by geodetic (group delay) VLBI
   Solution: phase referencing between star (faint) and (CN (bright))
  - $\rightarrow$  Solution: **phase-referencing** between star (faint) and AGN (bright)
- **Relative** star positions towards AGN position at specific frequency core:
  - Can be very precisely derived
  - Estimates for models of stellar motion
  - Precise proper motion is used for determination of the Gaia DR residual spin

Fig.: Estimated model of stellar motion for star AR Lac. The relative positions labelled by red asterisks (Lunz et al., 2021b, submitted to A&A).



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## Example: Alignment of Gaia DR to ICRF3

- **Absolute** star positions in ICRF3 S/X:
  - Commonly used procedure: add absolute calibrator position in ICRF3 S/X based on group delays
  - Used for determination of the orientation offset and the residual spin
- One of the largest error sources of absolute position is the (unkown) difference between phase delay position and group delay position of the AGN

 $\rightarrow$  on average 0.2 milliarcseconds

 $\rightarrow$  directly affects the formal error of the Gaia/ICRF3 alignment test

→ User requirement: S/X(/C) antenna capability, S/X/K/Ka/VGOS for astrophysical studies

Fig.: Orientation offset (top) and residual spin (bottom) between Gaia EDR3 and ICRF3 from data of 60 stars (Lunz et al., 2021b, submitted to A&A).



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Lunz et al., 2021a, submitted to A&A Lunz et al., 2021b, submitted to A&A

#### 3.c Determination of AGN core shift - VGOS

- VGOS observes AGN at 4 widely separated broad frequency bands
- Source structure and core shift are typically different at the 4 bands
- VGOS observations have very low thermal noise → source structure is dominant systematic error that has to be corrected for in the data analysis
  - $\rightarrow$  Relative source structure can be modeled from observations directly
  - → Alignment of the images relative to each other depends on assumptions (core shift is unknown!)
- → Observations of AGN at VGOS bands relative to the satellite are a unique chance to accurately address and solve this error source
- $\rightarrow$  User requirement: VGOS antenna capability



Xu et al., 2021b, JoG, 95, 51 Xu et al., 2021a, submitted to A&A Xu et al. IVS General Meeting 2022



#### 3.d Positive effects for EOP

- Earth Orientation Parameters (EOP) link the ITRF and ICRF
- Full set of EOP can only be determined by VLBI to AGN
- Celestial pole offsets (CPO; dX and dY) and dUT1 estimation is improved
  from enhanced CRF

 $R_1 \cong -dY; \quad R_2 \cong dX; \quad R_3 \cong dUT1/r' + A_Z$ 

r' ... ratio between solar and siderial time;  $A_Z$  ... part of global rotation wrt. TRF

- Polar motion is **correlated** to CPO and dUT1 $\rightarrow$  improved pole coordinates ( $x_P$ ,  $y_P$ )
- $\rightarrow$  Overall improved consistency of EOP and CRF

→ User requirement: S/X/K/Ka/VGOS antenna capability





#### 4. Recapitulation

- GENESIS can serve several applications for ICRF:
  - Simultaneous observations by various VLBI networks (e.g. S/X, K, X/Ka and VGOS)
     → Local tie in space
  - Unique chance to determine core shifts for all AGN precisely through phasereferencing between satellite and AGN
    - $\rightarrow$  Astrophysical studies and enhancement of the Gaia/VLBI frame alignment
    - → Correction of **source structure effects in VGOS**
  - Enhanced CRF has **positive effects on all EOP** → Overall improvement of any satellite application that requires POD
- Required frequencies:
  - S/X can be considered legacy, but important for ICRF stability and connection to ITRF
  - Include VGOS → future of geodetic VLBI
  - Include K-band and other higher frequencies (Ka)  $\rightarrow$  future of ICRF, spacecraft tracking

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#### 4. Recapitulation

- Design requirements:
  - Weak broadband noise (similar to AGN)
  - One antenna which emits all frequencies is optimal
  - Calibration at all frequencies on ground essential (position, structure of the emission)
  - Satellite orientation in space has to be determined precisely
  - Satellite speed: slow enough for phase-referencing (nodding-style)

**Conclusion:** A co-location satellite is an outstanding opportunity to enhance the CRF and thereby indirectly obtain improved EOP

 $\rightarrow$  General improvement of all satellite applications that require POD





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#### Thank you very much for your attention.







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#### We are looking forward to the collaboration.

Current DFG Project: Alignment of Gaia-optical and radio reference frames (AGORA)



# Backup: polarization difference between legacy and VGOS sites

- Legacy antennas (S/X): right circular polarization (RCP)
  - → Transmitting antenna onboard satellite must produce left circular polarization (LCP) for optimal gain of the system
- VGOS antennas: two perpendicular linear polarizations
  - → Transmitting antenna onboard satellite must be unpolarized for optimal gain of the system → not possible → use circular polaization
- $\rightarrow$  Best for co-location satellite is LCP (Jaradat et al. 2021)
- → Two arms Archimedian Spiral Antenna is best as the fractional bandwith can be up to 40:1 (e.g. 1-40 GHz → covers all geodetic VLBI frequ.) without significant frequency dependence of radiation pattern and polarization (Klimya and Prakash 2015)



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